

The S13683-02WT is a color sensor that supports the inter-integrated circuit (I²C) interface. It is sensitive to red (λ p=615 nm), green (λ p=530 nm), blue (λ p=460 nm), and infrared (λ p=855 nm) light, and outputs detected results as 16-bit digital data for each color. The sensor automatically switches the photodiode of each color in order to perform measurements. The sensitivity and integration time are adjustable so that light measurements can be performed over a wide range. We provide an evaluation kit for this product. Contact us for detailed information.

Features

- **I²C** interface compatible
- Sequential measurements of red, green, blue, and infrared light
- **2**-step sensitivity switching (sensitivity ratio 1:10)
- Adjustable sensitivity (1 to 65535 times) by setting the integration time
- Low voltage (2.5 V or 3.3 V) operation
- **Δ** Low current consumption: 75 μA typ.
- With infrared cutoff filter
- **Wide dynamic range (low gain: 1 to 10 k***lx*)

Applications

- **LCD** backlight adjustment on cell phones, notebook PCs, etc.
- **Energy-saving sensors on wide screen TV, etc.**
- Various light level detection and chromaticity adjustment

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Absolute maximum ratings (Ta=25 °C unless otherwise noted)

Parameter	Symbol	Condition	Value	Unit
Supply voltage	Vdd		-0.3 to +4.5	V
Output current	Io		±10	mA
Power dissipation	Р		100	mW
Operating temperature	Topr	No dew condensation*1	-40 to +85	°C
Storage temperature	Tstg	No dew condensation*1	-40 to +100	°C
Reflow soldering conditions*2	Tsol		Peak temperature: 260 °C, three times (see P.11)	-

*1: When there is a temperature difference between a product and the surrounding area in high humidity environment, dew condensation may occur on the product surface. Dew condensation on the product may cause deterioration in characteristics and reliability.

*2: Moisture absorption and reflow conditions: JEDEC J-STD-020D LEVEL2a

Note: Exceeding the absolute maximum ratings even momentarily may cause a drop in product quality. Always be sure to use the product within the absolute maximum ratings.

Recommended operating conditions (Ta=25 °C unless otherwise noted)

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit
Supply voltage	Vdd		2.25	-	3.63	V
I ² C bus pull-up voltage* ³	Vbus	Rp=2.2 kΩ	1.65	-	Vdd + 0.5	V
High lovel input veltage (CDA, CCI)*4	Vib	Vbus≥2.25 V Vdd>2.75 V	0.7Vbus	-	Vdd + 0.5	V
High level input voltage (SDA, SCL)*4		Vbus<2.25 V Vdd≤2.75 V	0.8Vbus	-	Vdd + 0.5	V
Low lovel input veltage (CDA CCL)*4	Vil	Vbus≥2.25 V Vdd>2.75 V	-0.5	-	0.2Vbus	V
Low level input voltage (SDA, SCL)	VII	Vbus<2.25 V Vdd≤2.75 V	-0.5	-	0.3Vbus	V
Bus capacitance (SDA, SCL)	Chus		_	_	400	рF

*3: For details, see the I²C specifications, "The I²C-BUS SPECIFICATION VERSION 2.1".

*4: Vdd - Vbus<1.2 V

Operation is not guaranteed if this condition is not met.

Electrical and optical characteristics

Sensor section [Ta=25 °C, Vdd=Vbus=3.3 V, light source A (initial setting: low gain, integration time: 546 ms/ch), unless otherwise noted]

Paramet	er	Symbol		Condition	Min.	Тур.	Max.	Unit	
			Blue						
Sportral response	~ngo*5	λ.	Green			455 to 630		nm	
specular response i	ange	Λ	Red						
			Infrared	d, 700 nm or more					
			Blue		-	460	-		
Poak concitivity wa	volonath	٨n	Green		-	530	-	nm	
Peak sensitivity wa	velengun	vh	Red		-	615	-		
			Infrared	d, 700 nm or more	-	855	-		
Current concumption	Operation mode	Idd	E_0 h (d	lark stata) avaluding output surront	30	75	150		
Current consumption	Standby mode	Idds	$\int c = 0 ix (0$		0.1	1.0	3.0	μΑ	
Dark count		Sd	E=0 lx	(dark state), initial setting	-	-	5	counts	
Gain ratio		rg	High ga	in/Low gain	-	10	-	-	
		Sbl	Blue		2.01	3.35	4.69		
		Sgl	Green	Initial cotting	4.57	7.61	10.66		
		Srl	Red		5.69	9.48	13.28		
Dhotoconcitivity		Sirl	Infrared		-	1.66	-	counte//	
Photosensitivity	LOW Gain	Sbl	Blue		2.51	3.35	4.19		
	·	Sgl	Green	Initial cotting*6	5.71	7.61	9.52		
			Srl	Red		7.11	9.48	11.85	
		Sirl	Infrared		-	1.66	-		
Red/Blue sensitivity ratio		Srl/Sbl	Initial a	atting	2.12	2.83	3.54		
Red/Green sensitivity ratio	Low gain	Srl/Sgl	Same c	hin	0.93	1.25	1.56	-	
Blue/Green sensitivity ratio		Sbl/Sgl	Same c	ΠÞ	0.33	0.44	0.55		
		Sbh	Blue		19.0	31.7	44.4		
		Sgh	Green	Integration time: 546 mc/ch	45.7	76.2	106.7		
		Srh	Red	integration time. 540 ms/cm	56.7	94.5	132.4		
Dhotoconcitivity	High goin	Sirh	Infrared		-	15.3	-	counte//	
Photosensitivity	nığı yalı	Sbh	Blue		23.8	31.7	39.7		
		Sgh	Green	Integration times EAC me/ob*6	57.2	76.2	95.3		
		Srh	Red	integration time. 546 ms/ch	70.9	94.5	118.2		
		Sirh	Infrared		-	15.3	-		
Red/Blue sensitivity ratio		Srh/Sbh	Intogra	tion times 546 mg/gh	2.24	2.98	3.73		
Red/Green sensitivity ratio High gain		Srh/Sgh	gh Same chin		0.93	1.24	1.55	-	
Blue/Green sensitivity ratio	Sbh/Sgh		in P	0.31	0.42	0.52			

*5: In the range of 10% from the peak

*6: When integration time is measured and corrected. See "Sensitivity variation correction method." The measurement accuracy of integration time is 0.36%.



I ² C section (Ta=25 °C, Vdd=Vbus=3.3 V, unles	s otherwise noted)
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Parameter	•	Symbol	Condition	Min.	Тур.	Max.	Unit			
I ² C address		ADDR	7-bit	0	0x2A (0101010)					
I ² C clock frequency		fclk		1	-	400	kHz			
	High level	Voh	Rp=2.2 kΩ	0.7Vbus	-	-	V			
SDA, SCL OULPUL VOILAGE	Low level	Vol	Rp=2.2 kΩ	0	-	0.4	V			
I/O terminal capacita	ance	Ci		-	-	20	pF			
SDA/SCL output fall time* ⁷ tf		Rp=2.2 kΩ, Cp=400 pF	-	-	250	ns				

Note: The I²C interface (SDA, SCL) timings conform to the "I²C-bus specification version 2.1".

*7: The SCL/SDA output rise time is determined by the time constant of Cbus \times Rp.

Register map

Adro	Function											
Aurs	TUTCION	7	6	5	4	3	2	1	0			
00	Control	ADC reset 1: reset 0: operation start	Standby function 1: standby mode 0: operation mode	Standby function monitor	-	Gain selection 1: high gain 0: low gain	Integration mode 1: manual setting mode 0: fixed time mode	Integration (00) 87.5 μs, (10) 22.4 ms,	time setting (01) 1.4 ms (11) 179.2 ms			
01	Manual timing register		Integration time manual setting register (high byte)									
02		Integration time manual setting register (low byte)										
03	Sensor's data register			Οι	ltput	data (red, hi	gh byte)					
04	(Red)			0	utput	data (red, lo	w byte)					
05	Sensor's data register			Out	put d	lata (green, h	nigh byte)					
06	(green)			Ou	tput d	data (green, l	ow byte)					
07	Sensor's data register			Ou	tput	data (blue, hi	igh byte)					
08	(Blue)		Output data (blue, low byte)									
09	Sensor's data register		Output data (infrared, high byte)									
0A	(Infrared)			Out	out d	ata (infrared,	low byte)					

Adrs 00 bit 7: Set this bit to 1 to reset the ADC section. This does not reset the register data. Set this bit to 0 to start operation.

Adrs 00 bit 6: Set this bit to 1 to switch to standby mode. The ADC section will stop its operation. This does not reset the register data.

Adrs 00 bit 5: This bit is used to monitor the auto standby function. When set to 1, the sensor is in standby mode. This bit is read-only. Adrs 00 bit 3: Set this bit to 1 for high gain and 0 for low gain. The area ratio of the photodiodes used for high gain and low gain is

10:1. As such, the gain ratio is 10.

- Adrs 00 bit 2: Set this bit to 1 to switch to manual setting mode and 0 to switch to fixed time mode. In manual setting mode, the sensor automatically switches to standby mode after a measurement is made.
 - In fixed time mode, measurements are repeated continuously.
- Adrs 00 bit 1,0: Select the integration time per color for fixed time mode. "00" is 87.5 μ s, "01" is 1.4 ms, "10" is 22.4 ms, and "11" is 179.2 ms. In manual setting mode, the reference is twice this time, so "00" is 175 μ s, "01" is 2.8 ms, "10" is 44.8 ms, and "11" is 358.4 ms. You can set an integer multiple of this value.
- Adrs 01 & 02: Integer multiple time setting valid only in manual setting mode. You can set a value between 0x0000 (minimum) and 0xFFFF (65535, maximum). Set how many times to make the integration time set with the integration time setting (Tint) longer. For example, if you want to set the integration time per color to 546 ms, set Tint to "00" to select 175 μ s, and set this register to N=3120 (0xC30).

Adrs 03 to 0A: The sensor measurement results are stored in these registers. These values are retained until the next measurement.

Initial setting [low gain, manual setting mode, Tint=00 (175 μs), integration time: 546 ms/ch]

This product has a built-in power-on reset function. After about 3 ms of delay time after the power is turned on, the registers are set to the default values shown in the following table.

Adrs	Function		bit											
		7	6	5	4	3	2	1	0	TIEX				
00	Control	1	1	1	-	0	1	0	0	0xE4				
01	Manual timing register	0	0	0	0	1	1	0	0	0x0C				
02		0	0	1	1	0	0	0	0	0x30				



Integration time setting

Mode	Manual timing register	Integration time setting (Tint)							
Mode	(Adrs 01 & 02)	00	01	10	11				
Fixed time mode	Invalid	87.5 μs	1.4 ms	22.4 ms	179.2 ms				
Manual setting mode	N	175 × N µs	2.8 × N ms	44.8 × N ms	358.4 × N ms				

Program example

Condition 1: Initial setting [manual setting mode, low gain, Tint=00 (175 µs), manual timing=3120 (0x0C30), integration time: 546 ms/ch]

Command

Action					Data	body				Ack	Remark
Address call (0x2A)	S	0	1	0	1	0	1	0	W	Α	7-bit address
Register call (0x00)		0	0	0	0	0	0	0	0	Α	Specifies the control byte
Register write (0x84)		1	0	0	0	0	1	0	0	Α	ADC reset, standby release
Address call (0x2A)	Sr	0	1	0	1	0	1	0	W	Α	Restart, address
Register call (0x00)		0	0	0	0	0	0	0	0	Α	Specifies the control byte
Register write (0x04)		0	0	0	0	0	1	0	0	Α	P ADC reset release, bus release
			St	ands	by for	· long	er tha	in the	integ	ration	time (>2184 ms)
Address call (0x2A)	S	0	1	0	1	0	1	0	W	Α	7-bit address
Register call (0x03)		0	0	0	0	0	0	1	1	Α	Specifies the output data byte
Address call (0x2A)	Sr	0	1	0	1	0	1	0	R	Α	Changes to read mode
Data read out (R: high byte)	Х	Х	Х	Х	Х	Х	Х	Х	A	Red data output
Data read out (R: low byte)		Х	Х	Х	Х	Х	Х	Х	Х	A	
Data read out (G: high byte	e)	Х	Х	Х	Х	Х	Х	Х	Х	Α	Croop data output
Data read out (G: low byte)		Х	Х	Х	Х	Х	Х	Х	Х	Α	
Data read out (B: high byte)	Х	Х	Х	Х	Х	Х	Х	Х	Α	Plue data output
Data read out (B: low byte)		Х	Х	Х	Х	Х	Х	Х	Х	Α	
Data read out (infrared: high b	byte)	Х	Х	Х	Х	Х	Х	Х	Х	A	Infrared data output
Data read out (infrared: low b	yte)	Х	Х	Х	Х	Х	Х	Х	Х	Ā	P

S=Start condition, Sr=Restart condition, A=Acknowledge, A=Acknowledge by host, P=Stop condition, R=Read mode (1), W=Write mode (0), \overline{A} =not acknowledge

Format

The s	same as the above comma	nd lis	st								
S	0x2A (7-bit)	W	Α		0x00	A 0x84		0x84	A		
	Sr 0x2A (7-bit)		W	/ A	0x00		Α	0x04		Α	Ρ
Wher	n the SCL clock is 400 kHz	, the	write	e time	is 135 µs.						
Stand	lby										
S	0x2A (7-bit)	W	А		0x03	Α	Sr	0x2A (7-bit)	R	А	
	Sensor data		Α		Sensor data	A]				
	Sensor data		Α		Sensor data	A					
	Sensor data		Α		Sensor data	A					
	Sensor data		Α		Sensor data	Ā	Р				
The readout time is 247.5 µs.											
	from master to slave	[from	slave to master						
	_										KP

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Condition 2 [fixed time mode, high gain, Tint=01 (1.4 ms), integration time: 1.4 ms/ch]

Command

Action					Data	body				Ack	Remark
Address call (0x2A)	S	0	1	0	1	0	1	0	W	Α	7-bit address
Register call (0x00)		0	0	0	0	0	0	0	0	Α	Specifies the control byte
Register write (0x89)		1	0	0	0	1	0	0	1	Α	ADC reset, standby release
Address call (0x2A)	Sr	0	1	0	1	0	1	0	W	Α	7-bit address
Register call (0x00)		0	0	0	0	0	0	0	0	Α	Specifies the control byte
Register write (0x09)		0	0	0	0	1	0	0	1	Α	P ADC reset release, bus release
Stands by for longer than	the i	ntegra	tion t	ime. N	1easu	remen	t is pe	erform	ed du	ring st	andby. (> 5.6 ms) Measurements are repeated continuously.
Address call (0x2A)	S	0	1	0	1	0	1	0	W	Α	7-bit address
Register call (0x03)		0	0	0	0	0	0	1	1	Α	Specifies the output data byte
Address call (0x2A)	Sr	0	1	0	1	0	1	0	R	Α	Changes to read mode
Data read out (R: high byte	e)	Х	Х	Х	Х	Х	Х	Х	Х	A	Red data output
Data read out (R: low byte))	Х	Х	Х	Х	Х	Х	Х	Х	A	
Data read out (G: high byte	e)	Х	Х	Х	X	Х	Х	Х	Х	A	Green data output
Data read out (G: low byte))	Х	Х	Х	Х	Х	Х	Х	Х	A	
Data read out (B: high byte	2)	Х	Х	Х	Х	Х	Х	Х	Х	A	Rhue data output
Data read out (B: low byte))	Х	Х	Х	Х	Х	Х	Х	Х	A	
Data read out (infrared: high	byte)	Х	Х	Х	Х	Х	Х	Х	Х	A	Infrared data output
Data read out (infrared: low b	yte)	Х	Х	Х	Х	Х	Х	Х	Х	Ā	P

S=Start condition, Sr=Restart condition, A=Acknowledge, A=Acknowledge by host, P=Stop condition, R=Read mode(1), W=Write mode(0), \overline{A} =not acknowledge

Format

The s	The same as the above command list												
S	0x2A (7-bit)	W	Α		0x00	Α		0x89	Α				
	Sr 0x2A (7-bit)		W	' A	0x00		Α	0x09		Α	Ρ		
When	n the SCL clock is 400 kHz	, the	write	e time	is 135 µs.								
Standby													
S	0x2A (7-bit)	W	А		0x03	A	Sr	0x2A (7-bit)	R	А			
	Sensor data		Α		Sensor data	A							
	Sensor data		Α		Sensor data	A							
	Sensor data		Α		Sensor data	A							
	Sensor data		A		Sensor data	Ā	Р						
The readout time is 247.5 µs.													
	from master to slave			from	slave to master								
	_										KPICC0327E/		



Condition 3 [manual setting mode, high gain, Tint=01 (2.8 ms), manual timing=357 (0x165), integration time: 1.0 s/ch]

Command

Action		Data body								Ack	Remark			
Address call (0x2A) S	(0	1	0	1	0	1	0	W	Α	7-bit address			
Register call (0x00)	(0	0	0	0	0	0	0	0	A	Specifies the control byte			
Register write (0x8D)		1	0	0	0	1	1	0	1	Α	ADC reset, standby release			
Register write (0x01)	(0	0	0	0	0	0	0	1	Α	Manual timing high byte			
Register write (0x65)	(0	1	1	0	0	1	0	1	A	Manual timing low byte			
Address call (0x2A) S	r (0	1	0	1	0	1	0	W	A	7-bit address			
Register call (0x00)	(0	0	0	0	0	0	0	0	A	Specifies the control byte			
Register write (0x0D)	(0	0	0	0	1	1	0	1	A	P ADC reset release, bus release			
Stands by for longer than the integration time. Measurement is performed during standby. (> 4.0 s) Measurements are repeated continuously.														
Address call (0x2A) S		0	1	0	1	0	1	0	W	A	7-bit address			
Register call (0x03)	(0	0	0	0	0	0	1	1	A	Specifies the sensor data byte			
Address call (0x2A) S	r (0	1	0	1	0	1	0	R	A	Changes to read mode			
Data read out (R: high byte)		X	Х	X	Х	Х	X	Х	Х	A	Red data output			
Data read out (R: low byte)		X	Х	Х	Х	Х	Х	Х	Х	A				
Data read out (G: high byte)		X	Х	Х	Х	Х	Х	Х	Х	A	Green data output			
Data read out (G: low byte)		X	Х	Х	Х	Х	Х	Х	Х	A				
Data read out (B: high byte)		X	Х	X	Х	Х	X	Х	Х	A	Rhue data output			
Data read out (B: low byte)		X	Х	Х	Х	Х	Х	Х	Х	A				
Data read out (infrared: high byte)		X	Х	Х	Х	Х	Х	Х	Х	A	Infrared data output			
Data read out (infrared: low byte)		X	Х	Х	Х	Х	Х	Х	Х	Ā	P			

S=Start condition, Sr=Restart condition, A=Acknowledge, A=Acknowledge by host, P=Stop condition, R=Read mode(1), W=Write mode(0), \overline{A} =not acknowledge

Format





Sensitivity variation correction method



Sensitivity variation can be decreased using the correction coefficient which is calculated from the integration time measurement result.

Integration time measurement

In case of integration time measurement, it is necessary to set manual setting mode. Set ADC reset to "0" to start measuring the integration time on the microcontroller side. Integration time Tmeas can be measured by checking Sleep monitor (Adrs00 bit5)="1."

Correction method

The correction coefficient and the sensitivity after correction are expressed with the following equation.

$$\begin{split} &\mathsf{K} = \frac{\mathsf{Tset}}{\mathsf{Tmeas}} \\ &\mathsf{S'} = \mathsf{S} \cdot \mathsf{K} \\ &\mathsf{K} \quad : \text{ correction coefficient} \\ &\mathsf{Tset} \quad : \text{ integration time (setting)} \\ &\mathsf{Tmeas} \quad : \text{ integration time (measurement)} \\ &\mathsf{S} \quad : \text{ Photosensitivity (measurement)} \\ &\mathsf{S'} \quad : \text{ Photosensitivity (correction)} \end{split}$$

Sensitivity variation can be reduced by using correction coefficient K.

Measurement accuracy of integration time

Loop delay time (Tunit) is the minimum Tmeas resolution. If Tunit is set to 7.8 ms, the integration time (Tset) under the initial setting becomes 546 ms \times 4 = 2184 ms, so the integration time measurement accuracy is expressed with the following equation.

$$\frac{\text{Tunit}}{\text{Tset}} \times 100 = \frac{7.8}{2184} \times 100 = 0.36\%$$

Count value vs. illuminance (typical example)





KPICB0238EA



Spectral response (typical example)

Block diagram



Timing chart of standby function



Connection example





Dimensional outline (unit: mm)



Tolerance unless otherwise noted: ± 0.05 Solder bump material: Sn (96.5%), Ag (3%), Cu (0.5%)

High gain mode

Enlarged view of photosensitive area (unit: μm)

KPICC0153EA



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Standard packing specifications

Reel (conforms to JEITA ET-7200)

Dimension	Hub diameter	Tape width	Material	Electrostatic characteris- tics		
180 mm	60 mm	8 mm	PS	-		

Embossed tape (unit: mm, material: PS, conductive)



Packing quantity 3000 pcs/reel

Packing type

Reel and desiccant in moisture-proof packaging (vacuum-sealed)



KPICC0317EA



- Measured example of temperature profile with our hot-air reflow oven for product testing

Time

KPICB0168EB

- This product supports lead-free soldering. After unpacking, store it in an environment at a temperature of 30 °C or less and a humidity of 60% or less, and perform soldering within a month.
- The effect that the product receives during reflow soldering varies depending on the circuit board and reflow oven that are used. When you set reflow soldering conditions, check that problems do not occur in the product by testing out the conditions in advance.

Related information

www.hamamatsu.com/sp/ssd/doc_en.html

- Precautions
- Disclaimer
- \cdot Metal, ceramic, plastic packages
- \cdot Surface mount type products

Evaluation kit for color sensor (S13683-02WT)

An evaluation kit [60 mm (H) \times 21.5 mm (V)] for understanding the operating principle of Hamamatsu's S13683-02WT color sensor is available. Contact us for detailed information.





RGB color sensor lineup

Туре по. Туре		Dhotoconsitivo area	Dackage	Peak sensitivity wavelength (nm)		Photosensitivity						Photo
		Photosensitive area	Раскауе									
		(mm)	(mm)									
S9032-02 Photodiode	Photodiada		$4 \times 4.8 \times 1.8^{t}$	В	460	В		0.18 (A/W) [λ=460 nm]			60 nm]	
	rnolouloue	φ2.0	6 pin	G	540	G		0.23 (A/W	/) [/	λ=5	40 nm]	
		(Filter 0.75 ^t)	R	620	R		0.16 (A/W	/) [/	λ=6	20 nm]	and the second	
S9702 Photodiode		$3 \times 4 \times 1.3^{t}$	В	460	В		0.18 (A/W	/) [/	λ=4	60 nm]		
	Photogloge	1.0×1.0	4 pin	G	540	G		0.23 (A/W	/) [λ=540 nm]			
			(Filter 0.75 ^t)	R	620	R		0.16 (A/W	/) [/	λ=6	20 nm]	4
S10917-35GT Photodiode	Distantia da		$3 \times 1.6 \times 1.0^{t}$	В	460	В		0.2 (A/W) [λ=460 nm]			
	Photodiode	1.0 × 1.0	COB	G	540	G		0.23 (A/W	√) [λ=540 nm]			
			(On-chip filter)	R	620	R		0.17 (A/W	/) [λ=620 nm]			
S10942-01CT Photodiode		$3 \times 1.6 \times 1.0^{t}$			В		0.21 (A/W) [λ=460 nm]					
	Photogloge	1.0×1.0	COB		*	G		0.25 (A/W	/) [λ=540 nm]			
			(On-chip filter)			R		0.45 (A/W	/) [λ=640 nm]			and the second
S9706 Digital photo IC	Distal		$4 \times 4.8 \times 1.8^{t}$ 6 pin (Filter 0.75 ^t)	В	465	_	В	0.21 (LSB/ <i>lx</i>)	_	В	1.9 (LSB/ <i>lx</i>)	
	Digital	1.2 × 1.2		G	540	No.	G	0.45 (LSB/ <i>lx</i>)	foit R	G	4.1 (LSB/ <i>lx</i>)	
				R	615	_	R	0.64 (LSB/ <i>lx</i>)		R	5.8 (LSB/ <i>lx</i>)	
S11012-01CR Digital photo IC	Disting		3.43 × 3.8 × 1.6 ^t COB		*	MO-	В	0.3 (LSB/ <i>lx</i>)	ligh	В	2.6 (LSB/ <i>lx</i>)	
	Digital	1.2 × 1.2					G	0.6 (LSB/ <i>lx</i>)		G	5.3 (LSB/ <i>lx</i>)	
		(On-chip filter)				R	1.4 (LSB/lx)	1	R	12.9 (LSB/ <i>lx</i>)		
S11059-02DT /-03DS	-2-		$3 \times 4.2 \times 1.3^{t}$ 10 pin	В	460		В	4.4 (count/ lx)	ł	В	44.8 (count/lx)	
	IC			G	530	≥	G	8.3 (count/ lx)		G	85.0 (count/lx)	
	compatible	0.56 × 1.22		R	615	Ĉ	R	11.2 (count/ lx)	ĭĔ	R	117.0 (count/ lx)	
	color sensor		(on-chip hiter)	IR	855		IR	3.0 (count/lx)	IR	IR	30.0 (count/lx)	
S13683-02WT co	I ² C compatible		1.75 × 1.25 ×0.48 ^t WL-CSP	R	615		R	9.48 (count/ lx)		R	94.5 (count/ lx)	-
				G	530	Low	G	7.61 (count/ lx)	High	G	76.2 (count/ lx)	
		1.22 × 0.56		В	460		В	3.35 (count/lx)		В	31.7 (count/ l_x)	
	color sensor		(on-chip filter)	IR	855		IR	1.66 (count/ <i>lx</i>)		IR	15.3 (count/ <i>lx</i>)	

* Refer to the spectral response of each product's datasheet.

The content of this document is current as of April 2018.

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