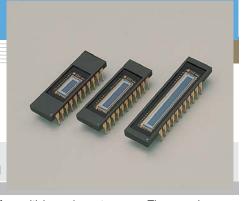
NMOS linear image sensor \$3901/\$3904 series

Current output, high UV sensitivity, excellent linearity, low power consumption



NMOS linear image sensors are self-scanning photodiode arrays designed specifically as detectors for multichannel spectroscopy. The scanning circuit is made up of N-channel MOS transistors, operates at low power consumption and is easy to handle. Each photodiode has a large active area, high UV sensitivity yet very low noise, delivering a high S/N even at low light levels. NMOS linear image sensors also offer excellent output linearity and wide dynamic range.

The photodiodes of S3901 series have a height of 2.5 mm and are arrayed in a row at a spacing of 50 µm. The photodiodes of S3904 series also have a height of 2.5 mm but are arrayed at a spacing of 25 µm. The photodiodes are available in 3 different pixel quantities for each series: 128 (S3901-128Q), 256 (S3901-256Q, S3904-256Q), 512 (S3901-512Q, S3904-512Q) and 1024 (S3904-1024Q). Quartz glass is the standard window material.

Features

- Wide active area
 - Pixel pitch: 50 µm (S3901 series) 25 µm (S3904 series)

Pixel height: 2.5 mm

- High UV sensitivity with good stability
- Low dark current and high saturation charge allow a long integration time and a wide dynamic range at room temperature
- Excellent output linearity and sensitivity spatial uniformity
- Lower power consumption: 1 mW max.
- Start pulse and clock pulses are CMOS logic compatible

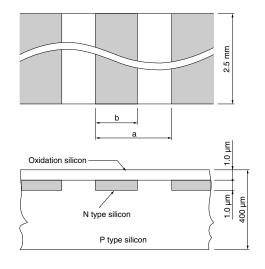
Applications

- Multichannel spectrophotometry
- Image readout system

■ Equivalent circuit

Start \$\phi st\$ Clock \$\phi 1\$ Clock \$\phi 2\$ Active photodiode Active photodiode Saturation control gate Saturation control drain Dummy diode Saturation control drain Dummy diode KMPDCCCC KMPDCCCC Saturation Saturation Saturation Saturation Saturation Control drain Dummy diode KMPDCCCC KMPDCCCC

■ Active area structure



S3901 series: a=50 μ m, b=45 μ m S3904 series: a=25 μ m, b=20 μ m

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Absolute maximum ratings

■ Absolute maximum ratings							
Parameter	Symbol	Value	Unit				
Input pulse (\$1, \$2, \$st) voltage	Vφ	15	V				
Power consumption*1	Р	1	mW				
Operating temperature*2	Topr	-40 to +65	°C				
Storage temperature	Tstg	-40 to +85	°C				

^{*1:} V ϕ =5.0 V

^{*2:} No dew

■ Shape specifications

Parameter	S3901-128Q	S3901-256Q	S3901-512Q	S3904-256Q	S3904-512Q	S3904-1024Q	Unit
Number of pixels	128	256	512	256	512	1024	-
Package length	31.75		40.6	31.75		40.6	mm
Number of pins	22			22			-
Window material*3	Quartz			Quartz			-
Weight	3.0		3.5	3.0		3.5	g

^{*3:} Fiber optic plate is available (excluding the S3901-128Q, S3904-256Q).

■ Specifications (Ta=25 °C)

Parameter	Symbol	S3901 series			S3904 series			Unit
		Min.	Тур.	Max.	Min.	Тур.	Max.	Offile
Pixel pitch	-	-	50	-	-	25	-	μm
Pixel height	-	-	2.5	-	-	2.5	-	mm
Spectral response range (10% of peak)	λ	200 to 1000		200 to 1000			nm	
Peak sensitivity wavelength	λр	-	600	-	-	600	-	nm
Photodiode dark current*4	ID	-	0.2	0.6	-	0.1	0.3	pА
Photodiode capacitance*4	Cph	-	20	-	-	10	-	pF
Saturation exposure*4 *5	Esat	-	180	-	-	180	-	$mlx \cdot s$
Saturation output charge*4	Qsat	-	50	-	-	25	-	рC
Photo response non-uniformity*6	PRNU	-	-	±3	-	-	±3	%

^{*4:} Vb=2.0 V, V ϕ =5.0 V

■ Electrical characteristics (Ta=25 °C)

Parameter		Symbol	Condition	S3901 series			S3904 series			Unit
				Min.	Тур.	Max.	Min.	Тур.	Max.	Unit
Clock pulse (\phi1, \phi2)	High	V ₀ 1, V ₀ 2 (H)		4.5	5	10	4.5	5	10	V
voltage	Low	Vφ1, Vφ2 (L)		0	-	0.4	0	-	0.4	V
Start pulse (het) voltage	High	V		4.5	V ₀ 1	10	4.5	V ₀ 1	10	V
Start pulse (\psi) voltage	Low	Vos (L)		0	-	0.4	0	-	0.4	V
Video bias voltage*7		Vb		1.5	Vø - 3.0	Vø - 2.5	1.5	V ₀ - 3.0	Vø - 2.5	V
Saturation control gate volt	age	Vscg		-	0	-	-	0	-	V
Saturation control drain vol		Vscd			Vb	-	-	Vb	-	V
Clock pulse (\phi1, \phi2) rise / fall time*8		tr\phi1, tr\phi2 tf\phi1, tf\phi2		1	20	ı	-	20	-	ns
Clock pulse (\phi1, \phi2) pulse w	idth	tpw\phi1, tpw\phi2		200	-	-	200	-	-	ns
Start pulse (ost) rise / fall ti	me	trφs, tfφs		1	20	-	-	20	-	ns
Start pulse (\pst) pulse width		tpwφs		200	-	-	200	-	-	ns
Start pulse (φst) and clock pulse (φ2) overlap		tφον		200	-	,	200	-	-	ns
Clock pulse space*8		X1, X2		trf - 20	-	-	trf - 20	-	-	ns
Data rate*9		f		0.1	-	2000	0.1	-	2000	kHz
			50% of	-	80 (-128 Q)	-	-	100 (-256 Q)	-	ns
Video delay time		tvd s	saturation	-	120 (-256 Q)	-	-	150 (-512 Q)	-	ns
•	•		*9 *10	-	160 (-512 Q)	-	-	200 (-1024 Q)	-	ns
Clock pulse (41 +2)				-	21 (-128 Q)	-	-	27 (-256 Q)	-	pF
Clock pulse (\phi1, \phi2) line capacitance		Сф	5 V bias	-	36 (-256 Q)	-	-	50 (-512 Q)	-	pF
				-	67 (-512 Q)	-	-	100 (-1024 Q)	-	pF
Saturation control gate (Vscg) line capacitance				-	12 (-128 Q)	-	-	14 (-256 Q)	-	pF
		Cscg	5 V bias	-	20 (-256 Q)	-	-	24 (-512 Q)	-	pF
				-	35 (-512 Q)	-	-	45 (-1024 Q)	-	pF_
VC 1		1 0	0.1/1:	-	7 (-128 Q)	-	-	10 (-256 Q)	-	pF
Video line capacitance		Cv 2 V	2 V bias	-	11 (-256 Q)	-	-	16 (-512 Q)	-	pF
				-	20 (-512 Q)	-	-	30 (-1024 Q)	-	pF

^{*7:} Vø is input pulse voltage (refer to "■Video bias voltage margin").

^{*5: 2856} K, tungsten lamp

^{*6: 50%} of saturation, excluding the start pixel and last pixel

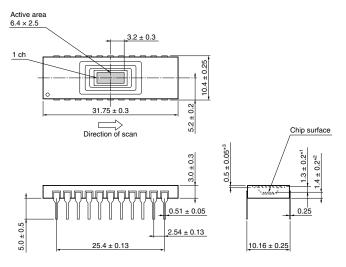
^{*8:} trf is the clock pulse rise or fall time. A clock pulse space of "rise time/fall time - 20" ns (nanoseconds) or more should be input if the clock pulse rise or fall time is longer than 20 ns (refer to "Timing chart for driver circuit").

^{*9:} Vb=2.0 V, Vφ=5.0 V

^{*10:} Measured with C7883 driver circuit.

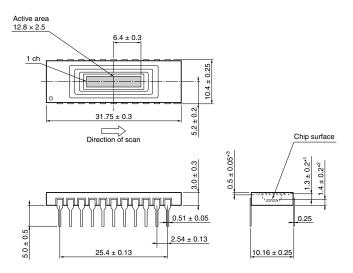
■ Dimensional outlines (unit: mm)

S3901-128Q, S3904-256Q



- *1: Distance from upper surface of quartz window to chip surface
- *2: Distance from chip surface to bottom of package
- *3: Window thickness

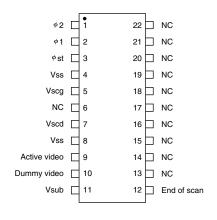
S3901-256Q, S3904-512Q



- *1: Distance from upper surface of quartz window to chip surface
 *2: Distance from chip surface
- to bottom of package
 *3: Window thickness

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■ Pin connection

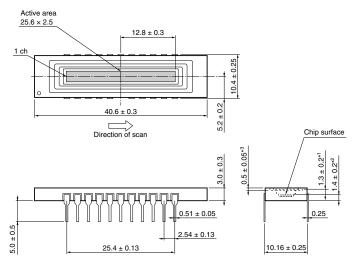


Vss, Vsub and NC should be grounded.

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S3901-512Q, S3904-1024Q

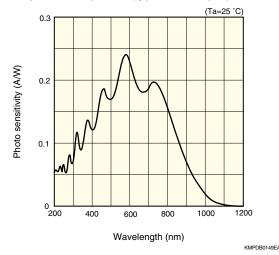


- *1: Distance from upper surface of quartz
- window to chip surface
 *2: Distance from chip surface
- to bottom of package

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Terminal	Input or output	Description				
φ1, φ2	Input (CMOS logic compatible)	Pulses for operating the MOS shift register. The video data rate is equal to the clock pulse frequency since the video output signal is obtained synchronously with the rise of ϕ 2 pulse.				
φst	Input (CMOS logic compatible)	Pulse for starting the MOS shift register operation. The time interval between start pulses is equal to the signal accumulation time.				
Vss	-	Connected to the anode of each photodiode. This should be grounded.				
Vscg	Input	Used for restricting blooming. This should be grounded.				
Vscd	Input	Used for restricting blooming. This should be biased at a voltage equal to the video bias voltage.				
Active video	Output	Video output signal. Connects to photodiode cathodes when the address is on. A positive voltage should be applied to the video line in order to use photodiodes with a reverse voltage. When the amplitude of \$\phi\$1 and \$\phi\$2 is 5 V, a video bias voltage of 2 V is recommended.				
Dummy video	Output	This has the same structure as the active video, but is not connected to photodiodes, so only spike noise is output. This should be biased at a voltage equal to the active video or left as an open-circuit when not needed.				
Vsub	-	Connected to the silicon substrate. This should be grounded.				
End of scan	Output (CMOS logic compatible)	This should be pulled up at 5 V by using a 10 k Ω resistor. This is a negative going pulse that appears synchronously with the $\phi 2$ timing right after the last photodiode is addressed.				
NC	-	Should be grounded.				

■ Spectral response (typical example)



■ Construction of image sensor

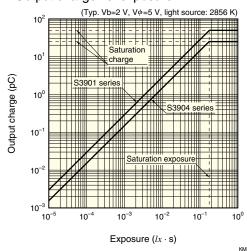
The NMOS image sensor consists of a scanning circuit made up of MOS transistors, a photodiode array, and a switching transistor array that addresses each photodiode, all integrated onto a monolithic silicon chip. "Equivalent circuit" shows the circuit of a NMOS linear image sensor.

The MOS scanning circuit operates at low power consumption and generates a scanning pulse train by using a start pulse and 2-phase clock pulses in order to turn on each address sequentially. Each address switch is comprised of an NMOS transistor using the photodiode as the source, the video line as the drain and the scanning pulse input section as the gate.

The photodiode array operates in charge integration mode so that the output is proportional to the amount of light exposure (light intensity \times integration time).

Each cell consists of an active photodiode and a dummy

Output charge vs. exposure



photodiode, which are respectively connected to the active video line and the dummy video line via a switching transistor. Each of the active photodiodes is also connected to the saturation control drain via the saturation control transistor, so that the photodiode blooming can be suppressed by grounding the saturation control gate. Applying a pulse signal to the saturation control gate triggers all reset. (See

"

Auxiliary functions".)

"Active area structure" shows the schematic diagram of the photodiode active area. This active area has a PN junction consisting of an N-type diffusion layer formed on a P-type silicon substrate. A signal charge generated by light input accumulates as a capacitive charge in this PN junction. The N-type diffusion layer provides high UV sensitivity but low dark current.

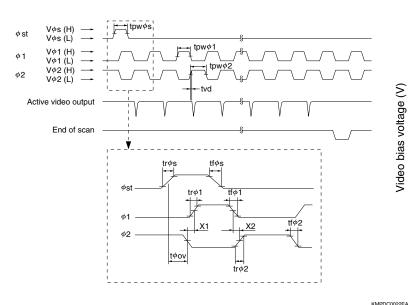
■ Driver circuit

S3901/S3904 series do not require any DC voltage supply for operation. However, the Vss, Vsub and all NC terminals must be grounded. A start pulse ϕ st and 2-phase clock pulses ϕ 1, ϕ 2 are needed to drive the shift register. These start and clock pulses are positive going pulses and CMOS logic compatible.

The 2-phase clock pulses $\phi 1$, $\phi 2$ can be either completely separated or complementary. However, both pulses must not be "High" at the same time.

A clock pulse space (X1 and X2 in "■Timing chart for driver circuit") of a "rise time/fall time - 20" ns or more should be input if the rise and fall times of φ1, φ2 are longer than 20 ns. The φ1 and φ2 clock pulses must be held at "High" at least 200 ns. Since the photodiode signal is obtained at the rise of each φ2 pulse, the clock pulse frequency will equal the video data rate.

Timing chart for driver circuit



■ Signal readout circuit

There are two methods for reading out the signal from an NMOS linear image sensor. One is a current detection method using the load resistance and the other is a current integration method using a charge amplifier. In either readout method, a positive bias must be applied to the video line because photodiode anodes of NMOS linear image sensors are set at 0 V (Vss).

"■Video bias voltage margin" shows a typical video bias voltage margin. As the clock pulse amplitude is higher, the video bias voltage can be set larger so the saturation charge can be increased. The rise and fall times of the video output waveform can be shortened if the video bias voltage is reduced while the clock pulse amplitude is still higher. When the amplitude of $\phi 1$, $\phi 2$ and ϕst is 5 V, setting the video bias voltage at 2 V is recommended.

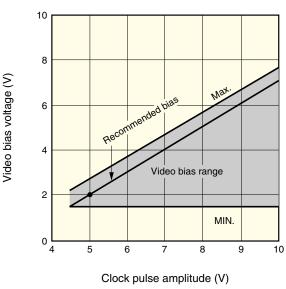
To obtain good linearity, using the current integration method is advised. In this method, the integration capacitance is reset to the reference voltage level immediately before each photodiode is addressed and the signal charge is then stored as an integration capacitive charge when the address switch turns on. "■Readout circuit example" and "■Timing chart" show a typical current integration circuit and its pulse timing chart. To en-

The amplitude of start pulse \$\phi\$st is the same as the \$\phi\$1 and \$\phi^2\$ pulses. The shift register starts the scanning at the "High" level of \$\phi\$st, so the start pulse interval determines the length of signal accumulation time. The \$\phi\$st pulse must be held "High" at least 200 ns and overlap with \$\phi^2\$ at least for 200 ns. To operate the shift register correctly, \$\phi^2\$ must change from the "High" level to the "Low" level only once during "High" level of \$\phi\$st. The timing chart for each pulse is shown in "■Timing chart for driver circuit".

■ End of scan

The end of scan (EOS) signal appears in synchronization with the $\phi 2$ timing right after the last photodiode is addressed, and the $\overline{\text{EOS}}$ terminal should be pulled up at 5 V using a 10 $k\Omega$ resistor.

■ Video bias voltage margin



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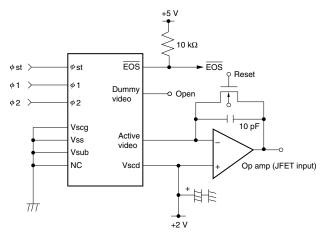
sure stable output, the rise of a reset pulse must be delayed at least 50 ns from the fall of $\phi 2$.

Hamamatsu provides the following driver circuits and related products (sold separately).

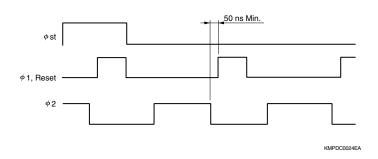
Product name	Type No.	Content	Feature		
	C7884	Precision driver circuit	Low noise Good output linearity		
Driver	C7884G	C7884 + C8225-01	Boxcar waveform output		
circuit	C7884-01	High precision driver circuit	Ultra-low noise Good output linearity		
	C7884G-01	C7884-01 + C8225-01	Boxcar waveform output		
Pulse generator	C8225-01	C7884 series			

NMOS linear image sensor S3901/S3904 series

■ Readout circuit example



■ Timing chart



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Output voltage Vout is expressed by the following equation. Vout [V] = $\frac{\text{Output charge [C]}}{10 \times 10^{-12} \text{ [F]}}$

■ Anti-blooming function

If the incident light intensity is higher than the saturation charge level, even partially, a signal charge in excess of the saturation charge cannot accumulate in the photodiode. This excessive charge flows out into the video line degrading the signal purity. To avoid this problem and maintain the signal purity, applying the same voltage as the video bias voltage to the saturation control drain and grounding the saturation control gate are effective. If the incident light intensity is extremely high, a positive bias should be applied to the saturation control gate. The larger the voltage applied to the saturation control gate, the higher the function for suppressing the excessive saturation charge will be. However, this voltage also lowers the amount of saturation charge, so an optimum bias voltage should be selected.

■ Auxiliary functions

(1) All reset

In normal operation, the accumulated charge in each photodiode is reset when the signal is read out. Besides this method that uses the readout line, S3901/S3904 series can reset the photodiode charge by applying a pulse to the saturation control gate. The amplitude of this pulse should be equal to the $\phi1$, $\phi2$ and ϕ st pulses and the pulse width should be longer than 5 μ s. When the saturation control gate is set at the "High" level, all photodiodes are reset to the saturation control drain potential (equal to video bias). Conversely, when the saturation control gate is set at the "Low" level (0 V), the signal charge accumulates in each photodiode without being reset.

(2) Dummy video

S3901/S3904 series have a dummy video line to eliminate spike noise contained in the video output waveform. Video signal with lower spike noise can be obtained by differential amplification applied between the active video line and dummy video line outputs. When not needed, leave this unconnected.

■ Handling precautions

(1) Electrostatic countermeasures

NMOS linear image sensors are designed to resist static electrical charges. However, take sufficient cautions and countermeasures to prevent damage from static charges when handling the sensors.

(2) Window

If dust or grime sticks to the surface of the light input window, it appears as a black blemish or smear on the image. Before using the image sensor, the window surface should be cleaned. Wipe off the window surface with a soft cloth, cleaning paper or cotton swab slightly moistened with organic solvent such as alcohol, and then lightly blow away with compressed air. Do not rub the window with dry cloth or cotton swab as this may generate static electricity.

NMOS linear image sensor S3901/S3904 series

Information described in this material is current as of February, 2014.

Product specifications are subject to change without prior notice due to improvements or other reasons. This document has been carefully prepared and the information contained is believed to be accurate. In rare cases, however, there may be inaccuracies such as text errors. Before using these products, always contact us for the delivery specification sheet to check the latest specifications.

The product warranty is valid for one year after delivery and is limited to product repair or replacement for defects discovered and reported to us within that one year period. However, even if within the warranty period we accept absolutely no liability for any loss caused by natural disasters or improper product

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HAMAMATSU PHOTONICS K.K., Solid State Division

1.26-1 Ichino-cho, Higashi-ku, Hamamatsu City, 435-8558 Japan, Telephone: (81) 53-434-3311, Fax: (81) 53-434-5184

U.S.A.: Hamamatsu Corporation: 360 Foothill Road, P.O.Box 6910, Bridgewater, N.J. 08807-0910, U.S.A., Telephone: (1) 908-231-0960, Fax: (1) 908-231-1218

Germany: Hamamatsu Photonics Deutschland GmbH: Arzbergerstr. 10, D-82211 Herrsching am Ammersee, Germany, Telephone: (49) 8152-375-0, Fax: (49) 8152-365-8

France: Hamamatsu Photonics France S.A.R.L.: 19, Rue du Saule Trapu, Parc du Moulin de Massy, 91882 Massy Cedex, France, Telephone: 33-(1) 69 53 71 00, Fax: 33-(1) 69 53 71 10

United Kingdom: Hamamatsu Photonics UK Limited: 2 Howard Court, 10 Tewin Road, Welvyn Garden City, Hertfordshire AL7 18W, United Kingdom, Telephone: (44) 1707-294888, Fax: (44) 1707-325777 North Europe: Hamamatsu Photonics Norden AB: Thorshamnsgatan 35 16440 Kista, Sweden, Telephone: (46) 8-509-031-00, Fax: (46) 8-509-031-01 Italy: Hamamatsu Photonics Italia S.R.L.: Strada della Moia, 1 int. 6, 20020 Arese, (Milano), Italy, Telephone: (39) 02-935-81-733, Fax: (39) 02-935-81-741 China: Hamamatsu Photonics (China) Co., Ltd.: 1201 Tower B, Jiaming Center, No.27 Dongsanhuan Beilu, Chaoyang District, Beijing 100020, China, Telephone: (86) 10-6586-6006, Fax: (86) 10-6586-2866