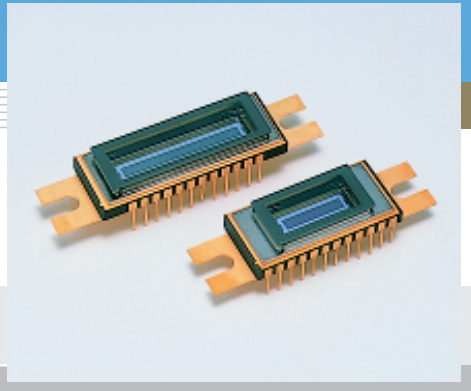


NMOS linear image sensor S5930/S5931 series



Built-in thermoelectric cooler ensures long exposure time and stable operation.

NMOS linear image sensors are self-scanning photodiode arrays designed specifically as detectors for multichannel spectroscopy. The scanning circuit is made up of N-channel MOS transistors, operates at low power consumption and is easy to handle. Each photodiode has a large active area, high UV sensitivity yet very low noise. The built-in thermoelectric cooler (air cooled) allows a long exposure time achieving a high S/N even at low light levels. The cap uses a sapphire glass window hermetically welded for high reliability.

Features

- Wide active area
Pixel pitch: 50 μm (S5930 series)
25 μm (S5931 series)
Pixel height: 2.5 mm
- High UV sensitivity with good stability
- Low dark current and high saturation charge allow a long integration time and a wide dynamic range at room temperature
- Excellent output linearity and sensitivity spatial uniformity
- Start pulse and clock pulses are CMOS logic compatible
- Built-in air-cooled thermoelectric cooler
(setting temperature: 0 °C)

Applications

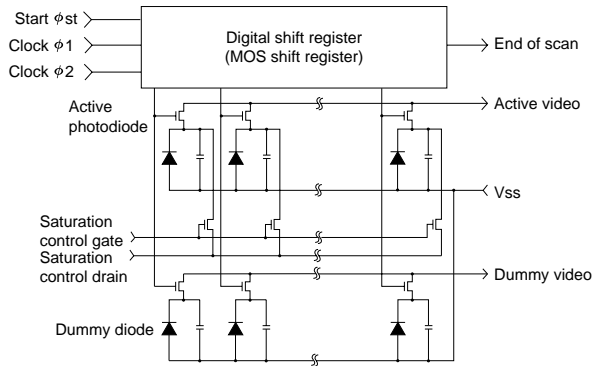
- Multichannel spectrophotometry
- Image readout system

■ Selection guide

Type No.	Number of pixels	Pixel size [μm (H) \times μm (V)]	Active area size [mm (H) \times mm (V)]
S5930-256S	256	50 \times 2500	12.8 \times 2.5
S5930-512S	512		25.6 \times 2.5
S5931-512S	512	25 \times 2500	12.8 \times 2.5
S5931-1024S	1024		25.6 \times 2.5

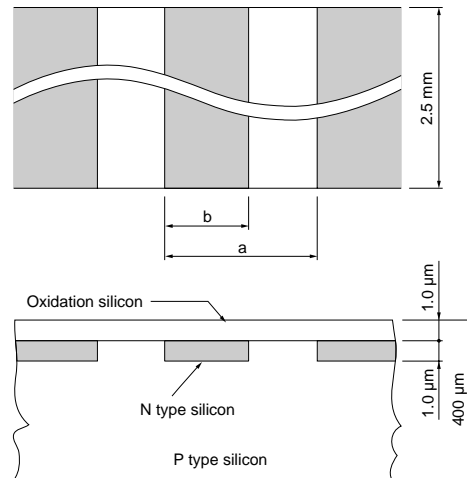
In addition to S5930/S5931 series, Hamamatsu provides S8382/S8383 series thermoelectrically cooled NMOS linear image sensors that offer higher sensitivity in the near IR range. Major characteristics of S8382/S8383 series are almost identical with S5930/S5931 series except that the peak sensitivity wavelength is 750 nm (see “■ Spectral response”) and the saturation charge is 90 $\text{mC} \cdot \text{s}$.

■ Equivalent circuit



KMPDC0020EA

■ Active area structure



S5930 series: a=50 μm, b=45 μm
S5931 series: a=25 μm, b=20 μm

KMPDA0132EA

■ Absolute maximum ratings

Parameter	Symbol	Condition	Value	Unit
Input pulse (φ1, φ2, φst) voltage	Vφ		15	V
Operating temperature *1	Topr	Ambient temperature *2	-40 to +65	°C
		Chip temperature	-40 to +50	°C
Storage temperature	Tstg		-40 to +85	°C

*1: No condensation

*2: The chip temperature should be monitored based on the thermistor resistance in order to keep the chip temperature within the rated range.

■ Specifications (Ta=25 °C, unless otherwise noted)

Parameter	Symbol	S5930 series			S5931 series			Unit	
		Min.	Typ.	Max.	Min.	Typ.	Max.		
Pixel pitch	-	-	50	-	-	25	-	μm	
Pixel height	-	-	2.5	-	-	2.5	-	mm	
Spectral response range (10% of peak)	λ	200 to 1000			200 to 1000			nm	
Peak sensitivity wavelength	λp	-	600	-	-	600	-	nm	
Photodiode dark current *3	Id	25 °C	-	0.2	0.6	-	0.1	0.3	pA
		0 °C	-	0.006	0.018	-	0.003	0.009	
Photodiode capacitance *3	Cph	-	20	-	-	10	-	pF	
Saturation exposure *3*4	Esat	-	180	-	-	180	-	m lx · s	
Saturation output charge *3	Qsat	-	50	-	-	25	-	pC	
Photo response non-uniformity *5	PRNU	-	-	±3	-	-	±3	%	

*3: Vb=2.0 V, Vφ=5.0 V

*4: 2856 K, tungsten lamp

*5: 50% of saturation, excluding the start pixel and last pixel

■ Electrical characteristics (Ta=25 °C)

Parameter	Symbol	Condition	S5930 series			S5931 series			Unit
			Min.	Typ.	Max.	Min.	Typ.	Max.	
Clock pulse ($\phi 1, \phi 2$) voltage	High	$V_{\phi 1}, V_{\phi 2}$ (H)	4.5	5	10	4.5	5	10	V
	Low	$V_{\phi 1}, V_{\phi 2}$ (L)	0	-	0.4	0	-	0.4	V
Start pulse (ϕ_{st}) voltage	High	$V_{\phi s}$ (H)	4.5	$V_{\phi 1}$	10	4.5	$V_{\phi 1}$	10	V
	Low	$V_{\phi s}$ (L)	0	-	0.4	0	-	0.4	V
Video bias voltage*6	V_b		1.5	$V_{\phi} - 3.0$	$V_{\phi} - 2.5$	1.5	$V_{\phi} - 3.0$	$V_{\phi} - 2.5$	V
Saturation control gate voltage	V_{scg}		-	0	-	-	0	-	V
Saturation control drain voltage	V_{scd}		-	V_b	-	-	V_b	-	V
Clock pulse ($\phi 1, \phi 2$) rise/fall time*7	$tr_{\phi 1}, tr_{\phi 2}$ $tf_{\phi 1}, tf_{\phi 2}$		-	20	-	-	20	-	ns
Clock pulse ($\phi 1, \phi 2$) pulse width	$tpw_{\phi 1}, tpw_{\phi 2}$		200	-	-	200	-	-	ns
Start pulse (ϕ_{st}) rise/fall time	$tr_{\phi s}, tf_{\phi s}$		-	20	-	-	20	-	ns
Start pulse (ϕ_{st}) pulse width	$tpw_{\phi s}$		200	-	-	200	-	-	ns
Start pulse (ϕ_{st}) and clock pulse ($\phi 2$) overlap	$t_{\phi ov}$		200	-	-	200	-	-	ns
Clock pulse space*7	X_1, X_2		$trf - 20$	-	-	$trf - 20$	-	-	ns
Data rate*8	f		0.1	-	2000	0.1	-	2000	kHz
Video delay time	t_{vd}	50 % of saturation*8*9	-	120 (-256S)	-	-	150 (-512S)	-	ns
			-	160 (-512S)	-	-	200 (-1024S)	-	ns
Clock pulse ($\phi 1, \phi 2$) line capacitance	C_{ϕ}	5 V bias	-	36 (-256S)	-	-	50 (-512S)	-	pF
			-	67 (-512S)	-	-	100 (-1024S)	-	pF
Saturation control gate (V_{scg}) line capacitance	C_{scg}	5 V bias	-	20 (-256S)	-	-	24 (-512S)	-	pF
			-	35 (-512S)	-	-	45 (-1024S)	-	pF
Video line capacitance	C_v	2 V bias	-	11 (-256S)	-	-	16 (-512S)	-	pF
			-	20 (-512S)	-	-	30 (-1024S)	-	pF

*6: V_{ϕ} is input pulse voltage.

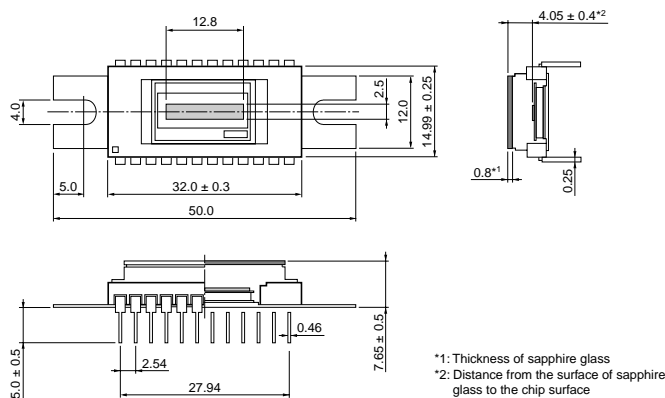
*7: trf is the clock pulse rise or fall time. A clock pulse space of "rise time/fall time - 20" ns (nanoseconds) or more should be input if the clock pulse rise or fall time is longer than 20 ns.

*8: $V_b=2.0$ V, $V_{\phi}=5.0$ V

*9: Measured with C7883 driver circuit.

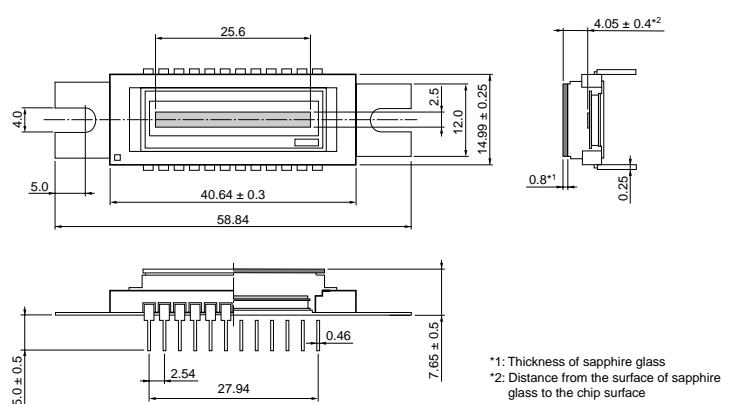
■ Dimensional outlines (unit: mm)

S5930-256S, S5931-512S



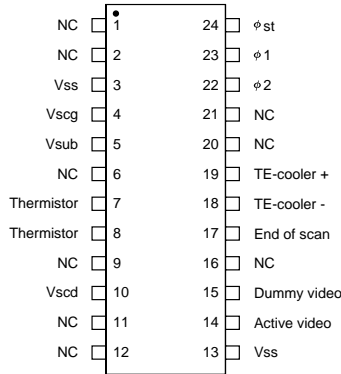
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S5930-512S, S5931-1024S



KMPDA0090JB

Pin connection

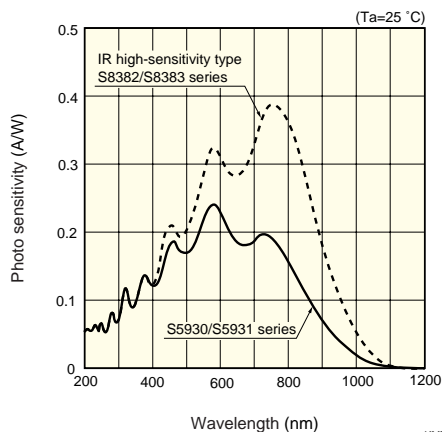


Vss, Vsub and NC should be grounded.
Electricity flows between the 20th pin and package metal.

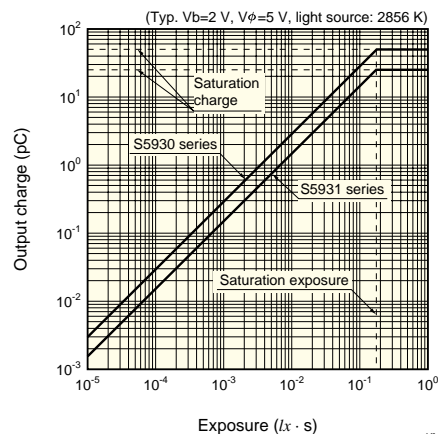
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Terminal	Input or output	Description
ϕ 1, ϕ 2	Input (CMOS logic compatible)	Pulses for operating the MOS shift register. The video data rate is equal to the clock pulse frequency since the video output signal is obtained synchronously with the rise of ϕ 2 pulse.
ϕ st	Input (CMOS logic compatible)	Pulse for starting the MOS shift register operation. The time interval between start pulses is equal to the signal accumulation time.
Vss	-	Connected to the anode of each photodiode. This should be grounded.
Vscg	Input	Used for restricting blooming. This should be grounded.
Vscd	Input	Used for restricting blooming. This should be biased at a voltage equal to the video bias voltage.
Active video	Output	Video output signal. Connects to photodiode cathodes when the address is on. A positive voltage should be applied to the video line in order to use photodiodes with a reverse voltage. When the amplitude of ϕ 1 and ϕ 2 is 5 V, a video bias voltage of 2 V is recommended.
Dummy video	Output	This has the same structure as the active video, but is not connected to photodiodes, so only spike noise is output. This should be biased at a voltage equal to the active video or left as an open-circuit when not needed.
Vsub	-	Connected to the silicon substrate. This should be grounded.
End of scan	Output (CMOS logic compatible)	This should be pulled up at 5 V by using a 10 k Ω resistor. This is a negative going pulse that appears synchronously with the ϕ 2 timing right after the last photodiode is addressed.
NC	-	Should be grounded.
TE-cooler	Input	For sensor chip cooling
Thermistor	Output	For temperature control

Spectral response (typical example)



Output charge vs. exposure



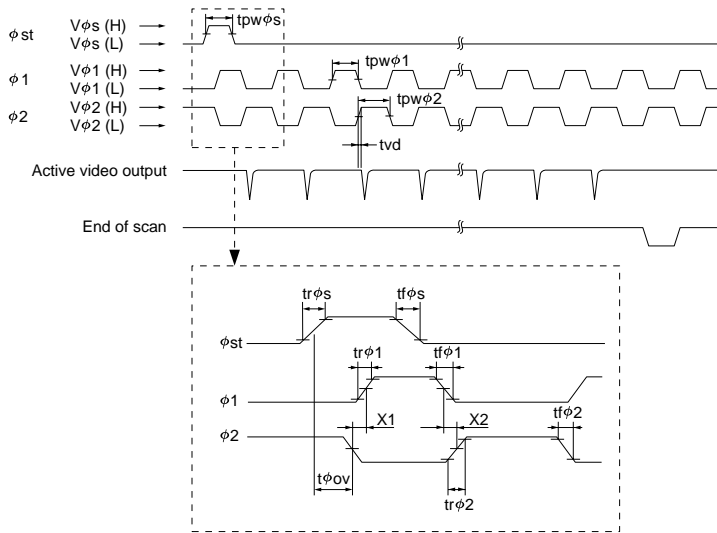
■ Driver circuit

S5930/S5931 series do not require any DC voltage supply for operation. However, the Vss, Vsub and all NC terminals must be grounded. A start pulse ϕ_{st} and 2-phase clock pulses ϕ_1 , ϕ_2 are needed to drive the shift register. These start and clock pulses are positive going pulses and CMOS logic compatible.

The 2-phase clock pulses ϕ_1 , ϕ_2 can be either completely separated or complementary. However, both pulses must not be “High” at the same time.

A clock pulse space (X1 and X2 in “■Timing chart for driver circuit”) of a “rise time/fall time - 20” ns or more should be input if the rise and fall times of ϕ_1 , ϕ_2 are longer than 20 ns. The ϕ_1 and ϕ_2 clock pulses must be held at “High” at least 200 ns. Since the photodiode signal is obtained at the rise of each ϕ_2 pulse, the clock pulse frequency will equal the video data rate.

■ Timing chart for driver circuit



■ Signal readout circuit

There are two methods for reading out the signal from an NMOS linear image sensor. One is a current detection method using the load resistance and the other is a current integration method using a charge amplifier. In either readout method, a positive bias must be applied to the video line because photodiode anodes of NMOS linear image sensors are set at 0 V (Vss). “■Video bias voltage margin” shows a typical video bias voltage margin. As the clock pulse amplitude is higher, the video bias voltage can be set larger so the saturation charge can be increased. The rise and fall times of the video output waveform can be shortened if the video bias voltage is reduced while the clock pulse amplitude is still higher. When the amplitude of ϕ_1 , ϕ_2 and ϕ_{st} is 5 V, setting the video bias voltage at 2 V is recommended.

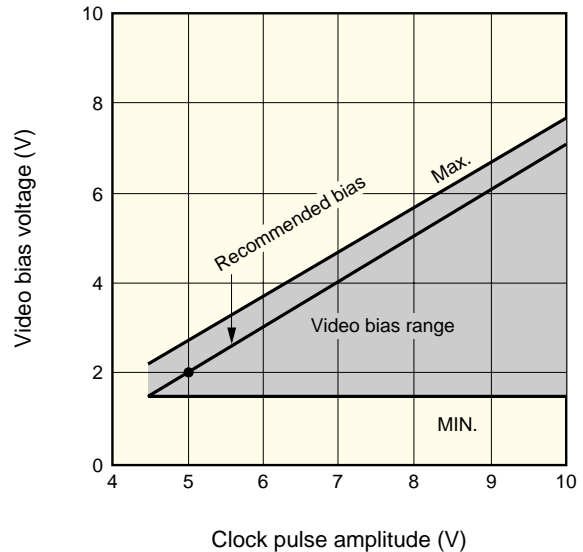
To obtain good linearity, using the current integration method is advised. In this method, the integration capacitance is reset to the reference voltage level immediately before each photodiode is addressed and the signal charge is then stored as an integration capacitive charge when the address switch turns on. “■Readout circuit example” and “■Timing chart” show a typi-

The amplitude of start pulse ϕ_{st} is the same as the ϕ_1 and ϕ_2 pulses. The shift register starts the scanning at the “High” level of ϕ_{st} , so the start pulse interval determines the length of signal accumulation time. The ϕ_{st} pulse must be held “High” at least 200 ns and overlap with ϕ_2 at least for 200 ns. To operate the shift register correctly, ϕ_2 must change from the “High” level to the “Low” level only once during “High” level of ϕ_{st} . The timing chart for each pulse is shown in “■Timing chart for driver circuit”.

■ End of scan

The end of scan (EOS) signal appears in synchronization with the ϕ_2 timing right after the last photodiode is addressed, and the EOS terminal should be pulled up at 5 V using a 10 k Ω resistor.

■ Video bias voltage margin

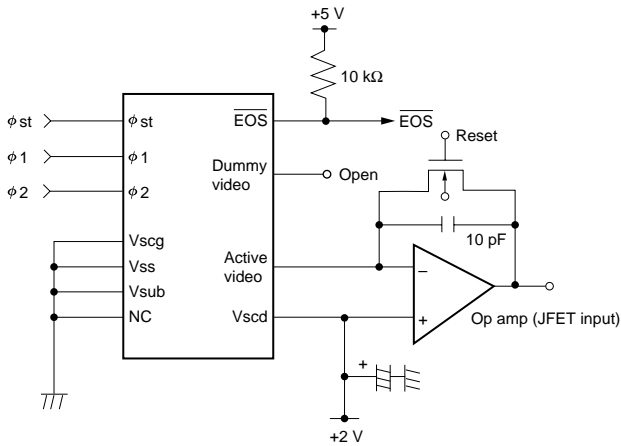


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cal current integration circuit and its pulse timing chart. To ensure stable output, the rise of a reset pulse must be delayed at least 50 ns from the fall of ϕ_2 .

■ Readout circuit example

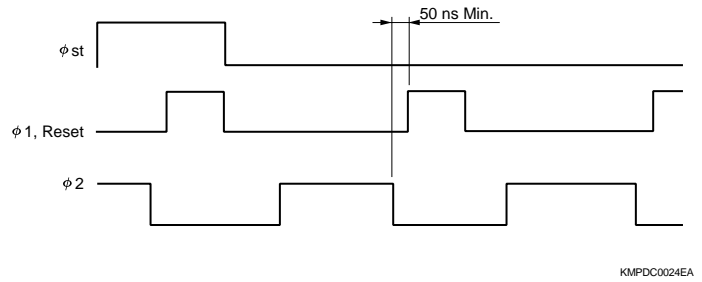


KMPDC0023EA

Output voltage V_{out} is expressed by the following equation.

$$V_{out} [V] = \frac{\text{Output charge [C]}}{10 \times 10^{-12} [F]}$$

■ Timing chart



KMPDC0024EA

■ Anti-blooming function

If the incident light intensity is higher than the saturation charge level, even partially, a signal charge in excess of the saturation charge cannot accumulate in the photodiode. This excessive charge flows out into the video line degrading the signal purity. To avoid this problem and maintain the signal purity, applying the same voltage as the video bias voltage to the saturation control drain and grounding the saturation control gate are effective. If the incident light intensity is extremely high, a positive bias should be applied to the saturation control gate. The larger the voltage applied to the saturation control gate, the higher the function for suppressing the excessive saturation charge will be. However, this voltage also lowers the amount of saturation charge, so an optimum bias voltage should be selected.

■ Auxiliary functions

(1) All reset

In normal operation, the accumulated charge in each photodiode is reset when the signal is read out. Besides this method that uses the readout line, S5930/S5931 series can reset the photodiode charge by applying a pulse to the saturation control gate. The amplitude of this pulse should be equal to the $\phi 1$, $\phi 2$ and ϕst pulses and the pulse width should be longer than $5 \mu s$. When the saturation control gate is set at the "High" level, all photodiodes are reset to the saturation control drain potential (equal to video bias). Conversely, when the saturation control gate is set at the "Low" level (0 V), the signal charge accumulates in each photodiode without being reset.

(2) Dummy video

S5930/S5931 series have a dummy video line to eliminate spike noise contained in the video output waveform. Video signal with lower spike noise can be obtained by differential amplification applied between the active video line and dummy video line outputs. When not needed, leave this unconnected.

■ Specifications of built-in TE-cooler (Typ.)

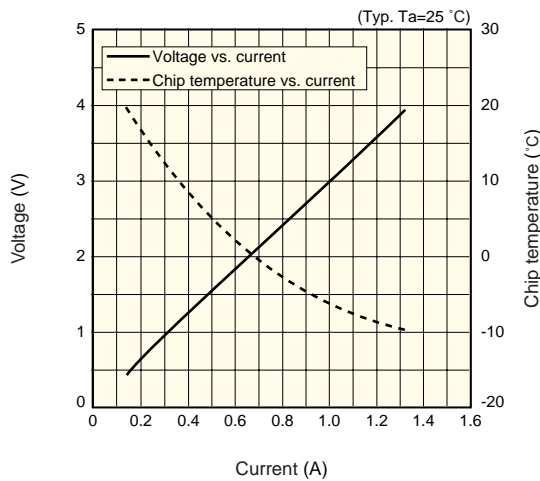
Parameter	Condition	S5930-256S, S5931-512S	S5930-512S, S5931-1024S	Unit
Internal resistance	Ta=25 °C	1.0	1.3	Ω
Maximum current*10	Th=27 °C	2.8	2.9	A
Maximum voltage*11	Th=27 °C	3.5	4.6	V
Maximum heat absorption	Tc=Th=27 °C	6.0	8.0	W
Maximum temperature difference	Th=27 °C	67		°C
Maximum temperature of heat radiating side		85		°C

*10: Electrical current required to generate the maximum difference between temperatures (temperature Th on the heat radiating side and temperature Tc on the cooling side) at both ends of the thermoelectric cooler while heat is completely insulated. Cooling efficiency will drop if operated at a current higher than this value.

*11: Voltage required for maximum current flow

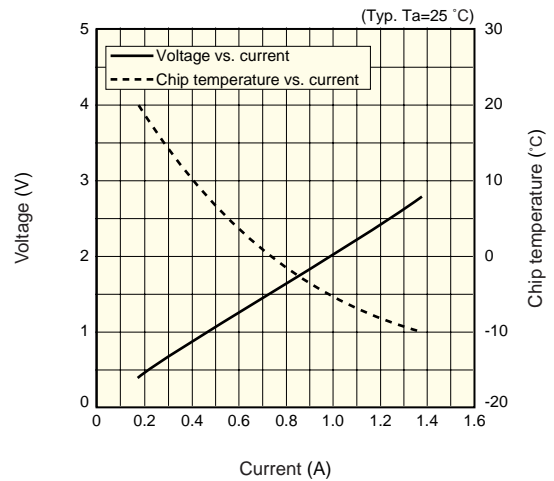
*12: Heat absorption amount when operated at maximum current. This is defined under the condition that the difference between the temperature Th on the heat radiating side and the temperature Tc on the cooling side is 0 °C.

S5930-512S, S5931-1024S



KMPDB0326EA

S5930-256S, S5931-512S



KMPDB0327EA

■ Specifications of built-in temperature sensor

A thermistor chip is built in the same package with a NMOS chip, and the chip temperature can be monitored with it, A relation between the thermistor resistance and absolute temperature is expressed by the following equation.

$$RT1 = RT2 \times \exp BT1/T2 (1/T1 - 1/T2)$$

RT1: Resistance at absolute temperature T1 [K]

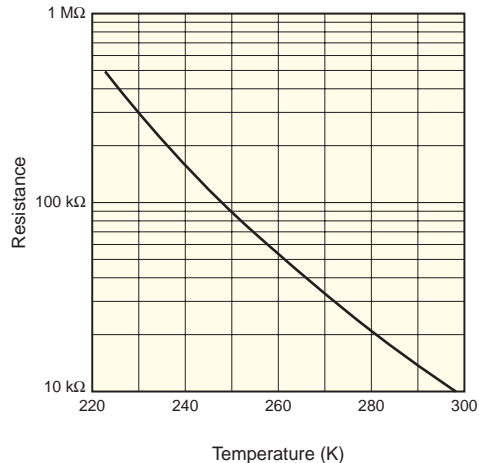
RT2: Resistance at absolute temperature T2 [K]

BT1/T2: B constant [K]

The characteristics of the thermistor used are as follows.

R298=10 kΩ

B298/323=3450 K



KMPDB0111EB

■ Precautions

(1) Electrostatic countermeasures

This device has a built-in protection circuit against static electrical charges. However, to prevent destroying the device with electrostatic charges, take countermeasures such as grounding yourself, the workbench and tools to prevent static discharges. Also protect this device from surge voltages which might be caused by peripheral equipment.

(2) Light input window

If dust or dirt gets on the light input window, it will show up as black blemishes on the image. When cleaning, avoid rubbing the window surface with dry cloth or dry cotton swab, since doing so may generate static electricity. Use soft cloth, paper or a cotton swab moistened with alcohol to wipe dust and dirt off the window surface. Then blow compressed air onto the window surface so that no spot or stain remains.

(3) Soldering

To prevent damaging the device during soldering, take precautions to prevent excessive soldering temperatures and times. Soldering should be performed within 5 seconds at a soldering temperature below 260 °C.

(4) Precautions when mounting

When installing the device into the socket on the printed circuit board, insert it in the correct orientation after checking the pin connections. Also take measures to protect this device from static electricity during this work. Never press on the surface of the device when inserting it into the circuit board, etc. Pressing on the sensor surface causes cracks and fractures in the window, possibly causing it to fall out and may lead to malfunctions.

- Insert the sensor into the socket while pressing on the sensor edges as shown in photo 1 or pressing on the screw hole sections as shown in photo 2.
- When securing the device by screws, place and secure it on a flat surface (flatness within 100 μm).
- Use a socket that matches the pin size and specifications.

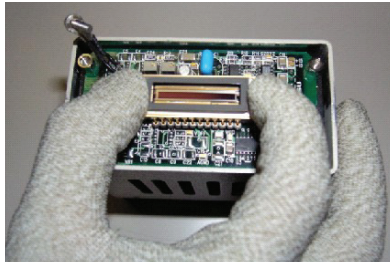


Photo 1

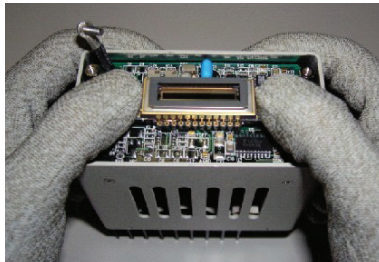


Photo 2

(5) Operating and storage environments

Always observe the rated temperature range when handling the device. Operating or storing the device at an excessively high temperature and humidity may cause variations in performance characteristics and must be avoided.

(6) UV exposure

This device is designed to suppress performance deterioration due to UV exposure. Even so, avoid unnecessary UV exposure to the device.

NMOS multichannel detector head C5964 series

The C5964 series is a family of multichannel detectors developed for spectrophotometry in the UV to near infrared range (up to 1000 nm). The C5964 series device incorporates a thermoelectrically-cooled NMOS linear image sensor (S5930/S5931/S8382/S8383 series), low noise driver/amplifier circuit and highly stable temperature control circuit. It also operates from simple external signal inputs.



■ Selection guide

The C5964 series consists of the following models depending on the NMOS linear image sensor used.

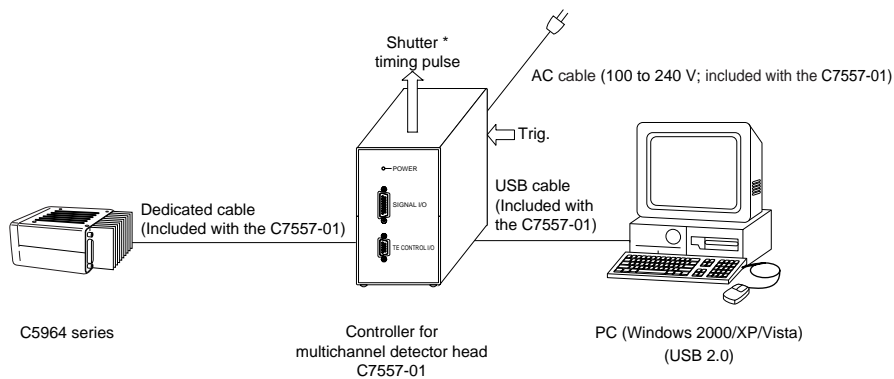
NMOS multichannel detector head	NMOS linear image sensor				Remark
	Type no.	Number of pixels	Pixel size [μm (H) \times μm (V)]	Active area [mm (H) \times mm (V)]	
C5964-0800	S5930-256S	256	50 \times 2500	12.8 \times 2.5	Standard type
C5964-0900	S5930-512S	512		25.6 \times 2.5	
C5964-0910	S5931-512S	512	25 \times 2500	12.8 \times 2.5	
C5964-1010	S5931-1024S	1024		25.6 \times 2.5	
C5964-0901	S8382-512S	512	50 \times 2500	25.6 \times 2.5	IR-enhanced type
C5964-1011	S8383-1024S	1024	25 \times 2500	25.6 \times 2.5	

Multichannel detector head controller C7557-01

The C7557-01 is specifically designed for basic control in multichannel photometry. When connected to a HAMAMATSU multichannel detector head and a personal computer, the C7557-01 allows easy control of the detector head and data acquisition by using dedicated software that comes with the unit.



■ Connection example



KACCC0070ED

Information described in this material is current as of August, 2014.

Product specifications are subject to change without prior notice due to improvements or other reasons. This document has been carefully prepared and the information contained is believed to be accurate. In rare cases, however, there may be inaccuracies such as text errors. Before using these products, always contact us for the delivery specification sheet to check the latest specifications.

The product warranty is valid for one year after delivery and is limited to product repair or replacement for defects discovered and reported to us within that one year period. However, even if within the warranty period we accept absolutely no liability for any loss caused by natural disasters or improper product use.

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